

Spatial-Temporal Hawkes Models of Infectious Disease Transmission with Covariates

Oral Exam

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Background & Motivation

Modeling infectious disease transmission is important for the purposes of:

- Forecasting the spread of infections
- Anticipating hospital demand
- Determining public health policy

Statistical Motivation

Compartment models (e.g., SEIR) are commonly used to model infections, but not without drawbacks.

- Restrictive assumptions lead to poor fit to real data [1, 2, 3].
- Neglect pertinent information such as: infectivity behavior dynamics, proximity, mobility, viral strains, etc.

Multivariate Hawkes process (MHP) models have been shown to offer a substantially superior fit [1].

- Suitable for explaining self-exciting events: causally-linked events wherein the occurrence increases the likelihood of subsequent events.
- Impactful examples:
 - Earthquakes [4]
 - Crime [5, 6]
 - Finance [7]
 - Social media [8]

Basic Temporal Hawkes Model Demonstration

$$\lambda(t) = \mu + K \sum_{s < t} \phi(\cdot)$$

where $\mu \geq 0$ represents the exogenous rate and $K \geq 0$ describes productivity [9]. In the example below, an exponential decay function is used as the triggering kernel, $\phi(\beta; t; s) = e^{-\beta(t-s)}$.

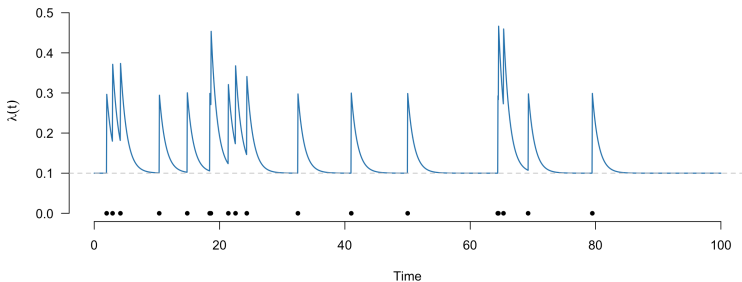


Figure 1: Simple Hawkes model demonstration, with $K = 0.2$, $\beta = 1.0$, $\mu = 0.1$.

Basic Spatial-Temporal Hawkes Model Demonstration

$$\lambda(t, x, y) = \mu + K \sum_{s < t} f(t - s) g(x - x_i, y - y_i). \quad (1)$$

where $f(\cdot)$ is the **temporal** triggering kernel and $g(\cdot)$ is the **spatial** triggering kernel.

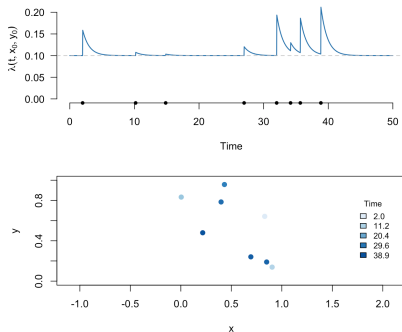


Figure 2: Simple spatial-temporal MHP model demonstration, with $\mu = 0.1$, $K = 0.2$, $\beta = 1.0$.
 $f(\cdot) = e^{-\beta(t-s)}$, $g(\cdot) = e^{-((x-x_i)^2 + (y-y_i)^2)/2\sigma^2}$

Conventional MHP Problem

Fitting a purely statistical MHP model exclusively to incidence data leads to **inflated** cross-productivity estimates, particularly among locations that are far apart [10, 11].

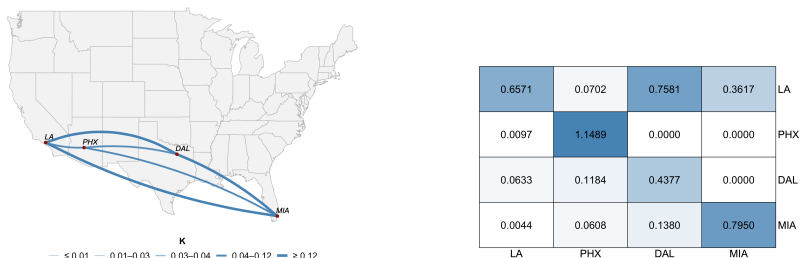


Figure 3: Estimated cross-productivities ($\hat{K}$) under the joint estimation framework. Fitted on COVID-19 data from March 12–July 20, 2020

Conventional Hawkes Problem Cont.

Large cross-productivity estimates can result when distant locations have similar temporal patterns as a product of global factors such as:

- Lockdown procedures
- Reporting behaviors
- Evolution of new viral strains

This leads the model to overestimate the rate of contagion between locations [10].

Conventional MHP models make **no use** of the distance/mobility between locations → **unaware** of the increasingly improbable contagion imposed by geographic barriers and/or low human mobility rates.

Research Goal

1. Develop a **covariate-informed MHP framework** to mitigate bias in estimated cross-productivities by incorporating a covariate-weighted penalty term w_{ij} , governed by:
 - i. Distance-based covariate D_{ij}
 - ii. Mobility-based covariate M_{ij}
2. Conduct a **systematic comparison** to test if distance- and mobility-based penalties reduce bias in cross-excitation estimates more effectively than existing regularization methods, in terms of **predictive performance** and **parameter recovery**.

This research is an extension of a paper by Diouane, Schoenberg, and Mohler [10] wherein various MHP modeling methods were compared to estimate cross-excitation with no use of covariates.

- Proposed a **sequential technique**:
 - **Stage 1**: purely temporal (i.e. local) models are independently fitted to each location and their parameters fixed.
 - **Stage 2**: inter-county models are fitted to residuals from **Stage 1** to obtain more accurate cross-excitation parameter estimates, indicating inter-county transmission.

Novel distinction: human mobility and spatial distance are used to penalize cross-productivity rates.

Preliminary Research

Data - COVID-19 in the United States

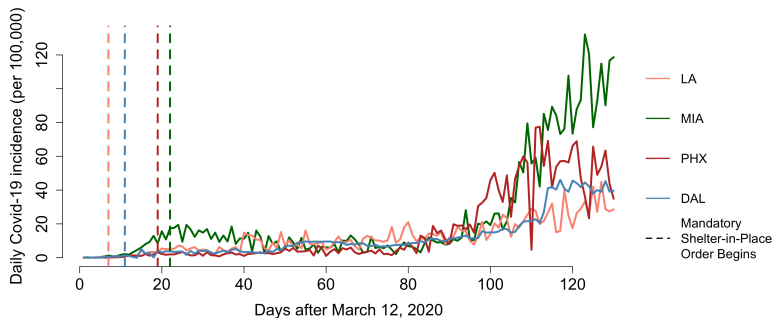


Figure 4: COVID-19 data were obtained from the NY Times Covid-19 GitHub repository, spanning 130 days from March 12–July 20, 2020 [12]. Los Angeles (LA), Miami-Dade (MIA), Maricopa (PHX), and Dallas (DAL) over 130 days starting after March 12, 2020. Data on mandatory shelter-in-place orders is obtained from U.S. Department of Health & Human Services [13].

Data - Distance Covariate

Locations are sourced from the R **maps** package. The Haversine formula is used to calculate the great-circle distance between locations:

$$D = 2 \cdot R \cdot \arcsin \sqrt{\sin^2 \left(\frac{x_2 - x_1}{2} \right) + \cos x_1 \cdot \cos x_2 \cdot \sin^2 \left(\frac{y_2 - y_1}{2} \right)}, \quad (2)$$

where D denotes distance, $R = 6378$ km describes Earth's radius, and (x_i, y_i) are the latitude and longitude of location i [14].

	LA	PHX	DAL	MIA
LA	0	589	2011	3776
PHX	589	0	1426	3186
DAL	2011	1426	0	1784
MIA	3776	3186	1784	0

Table 1: Pairwise distances between counties, measured in kilometers.

Data - Mobility Covariate

Cellphone location data are obtained from Kang et al. [15] are used to estimate the proportion of travelers going from location to location, calculated as follows:

Mobility from i to j is defined here as the proportion of travelers who leave i and arrive in j , $M_{ij} = n_{ij} / \sum_j n_{ij}$, where n_{ij} denotes the number of travelers from i to j during March–July 2020.

Data cover approximately 10% of the U.S. population, derived from anonymized cellphone location tracking, thereby accounting for all modes of transportation.

	LA	PHX	DAL	MIA
LA	0	0.82	0.10	0.08
PHX	0.86	0	0.08	0.06
DAL	0.47	0.32	0	0.21
MIA	0.51	0.22	0.27	0

Table 2: Pairwise mobility rates. Columns indicate origin while rows indicate destination.

Staged Hawkes Model

For each location $i = 1, \dots, Q$ on day $t = 1, \dots, T$, incidence is modeled with a discrete-time MHP,

$$\lambda_i(t|\mathcal{H}_{t-}) = \underbrace{\mu_i + K_{ii} \sum_{s < t} \phi_{\text{local}}(t, s; \beta_i, p_i) N_i(s)}_{\text{Stage 1 (local)}} + \underbrace{\sum_{j \neq i} K_{ij} \sum_{s < t} \phi_{\text{cross}}(t, s; \bar{\beta}_i, \bar{p}_i) N_j(s)}_{\text{Stage 2 (foreign)}} \quad (3)$$

- $\mathcal{H}_{t-}$ is the event history up to time t .
- $N_i(s) \in \{0, 1, 2, \dots\}$ is the recorded case count on day s
- $\phi_{\text{local}}(\cdot)$ and $\phi_{\text{cross}}(\cdot)$ are discretized Weibull triggering kernels given by

$$\phi(t, s; \beta, p) = (1 - p)^{(t-s-1)^\beta} - (1 - p)^{(t-s)^\beta}, 0 < p < 1, \beta > 0 \quad (4)$$

Estimate 1 - Joint Baseline

We first consider completely unconstrained parameters where $\theta = \{\mu_i, K_{ij}, \beta_i, p_i\}$, for $i, j = 1, 2, 3, 4$ is estimated jointly by MLE with no regularization and no constraints on the parameters other than $K_{ij} \geq 0, 0 < p < 1, \beta > 0$, and the subcriticality condition that specifies $\rho(K) < 1$.

$$\ell(\theta) = \sum_{i=1}^Q \sum_{t=1}^T \log \left(\frac{\lambda_i(t; \theta)^{N_i(t)}}{N_i(t)!} e^{-\lambda_i(t; \theta)} \right) \quad (5)$$

Such estimates tend to vastly overestimate cross-excitations, especially among distant locations [10].

Estimate 2 - Purely Univariate (Stage 1)

Here, we set $K_{ij} = 0$ for $i \neq j$ to force estimates to represent **purely local transmission**.

Local parameter estimates $\theta_{\text{local}} = \{\mu_i, K_{ii}, \beta_i, p_i\}_{i=1}^Q$ are obtained by MLE with elastic-net regularization on parameters K and β .

$$\max_{\theta_{\text{local}}} \ell_1(\theta_{\text{local}}) - \underbrace{\left(\frac{\alpha_1}{2} \sum_{i=1}^Q [\eta_1 K_{ii}^2 + \eta_2 \beta_i^2] + (1 - \alpha_1) \sum_{i=1}^Q [\eta_1 |K_{ii}| + \eta_2 |\beta_i|] \right)}_{\text{Elastic-Net Regularization}} \quad (6)$$

Estimate 3 - Staged with no Covariate Constraints

Two-stage procedure: local parameters $\hat{\theta}_{\text{local}}$ are estimated in **Stage 1** and held fixed, while cross-excitation parameters are estimated in **Stage 2**.

This prioritizes the local component:

- Most incidence is attributed locally.
- Reserves K_{ij} to capture only the residual clustering not explained by the local component.

Hence, with $\hat{\theta}_{\text{local}}$ fixed, cross-productivities $K_{i \neq j}$ are estimated by

$$\max_{K_{\text{cross}}} \ell_2(K_{\text{cross}} | \hat{\theta}_{\text{local}}) - \eta_3 \left[\frac{\alpha_2}{2} \sum_{i=1}^Q \sum_{j \neq i} K_{ij}^2 + (1 - \alpha_2) \sum_{i=1}^Q \sum_{j \neq i} |K_{ij}| \right] \quad (7)$$

Estimate 4 - Staged with Covariate Constraints

Here, we modulate $K_{i \neq j}$ by a covariate-derived weight w_{ij} determined by (i) spatial distance or (ii) human mobility.

$$\max_{K_{\text{cross}}} \ell_2(K_{\text{cross}} | \hat{\theta}_{\text{local}}) - \eta_3 \left[\frac{\alpha_2}{2} \sum_{i=1}^Q \sum_{j \neq i} w_{ij} K_{ij}^2 + (1 - \alpha_2) \sum_{i=1}^Q \sum_{j \neq i} w_{ij} |K_{ij}| \right]. \quad (8)$$

In (i) $w_{ij} \propto D_{ij}$ according to $w_{ij} = \exp(\delta D_{ij}^*)$ where D_{ij}^* is the standardized distance matrix, $D_{ij}^* = D_{ij} / \max_{i \neq j} D_{ij}$.

In (ii) $w_{ij} \propto 1/M_{ij}$ according to $w_{ij} = \exp(\gamma(1 - M_{ij}))$.

Both (i) and (ii) are structured in such a way as to shrink implausible long-range connections while preserving short-range transmission.

Elastic-net mixing parameters (α_1, α_2), strength parameters (η_1, η_2, η_3), and covariate scaling parameters (γ, δ) are tuned via grid search on a 104-day (80%) training window (March 12 - June 24) with a 26-day (20%) testing window (June 25–July 20).

Each stage is initialized with the **Genetic Algorithm** (GA) [16] followed by **optim** to refine the solution and compute standard errors.

Conducted a **Monte Carlo simulation** study for each covariate regime: (i) distance and (ii) mobility. For each, 100 independent datasets were generated to report mean parameter estimates and evaluation metrics.

Covariate matrices **D** and **M** are used to initiate the ground-truth system, allowing us to test the degree to which the model captures the effects of cross-excitation caused by trends in distance and mobility.

Focus is on recovery of reproduction matrix K and accuracy of out-of-sample predictions.

Simulation Results - Distance

Estimate	NLL	RMSE	$K_{i=j}$	$K_{i \neq j}$
True			0.795	0.042
Joint Baseline	6575.6 (389.2) [5812.7, 7338.6]	69.2 (2.8) [63.6, 74.7]	0.046 (0.009) [0.029, 0.064]	0.321 (0.006) [0.310, 0.333]
Univariate	1802.4 (30.9) [1741.9, 1862.9]	17.5 (0.6) [16.3, 18.8]	0.914 (0.005) [0.903, 0.924]	0.000 (0.000) [0.000, 0.000]
Staged Baseline	1781.9 (17.0) [1748.6, 1815.3]	17.3 (0.4) [16.5, 18.1]	0.914 (0.005) [0.903, 0.924]	0.003 (0.000) [0.002, 0.003]
Staged Distance Penalty	1781.9 (17.0) [1748.6, 1815.1]	17.3 (0.4) [16.5, 18.1]	0.914 (0.005) [0.903, 0.924]	0.002 (0.000) [0.002, 0.003]

Table 3: Distance setting. Pooled negative log-likelihood (NLL), pooled root mean squared error (RMSE), fitted diagonal (local) productivity ($\hat{K}_{i=j}$) and off-diagonal (cross) productivity ($\hat{K}_{i \neq j}$) across four estimation methods (mean with standard errors; 95% confidence intervals in brackets). Results from 100 simulations; true productivities shown for reference.

Simulation Results

0.8000	0.1669	0.0159	0.0009	A
0.1669	0.7900	0.0418	0.0023	B
0.0159	0.0418	0.8100	0.0231	C
0.0009	0.0023	0.0231	0.7800	D
A	B	C	D	

(a) Distance True

0.0438	0.3483	0.2734	0.4801	A
0.3875	0.0111	0.4321	0.4264	B
0.2786	0.1601	0.0330	0.4250	C
0.1460	0.1764	0.3131	0.0977	D
A	B	C	D	

(b) Distance Joint Baseline

0.9605	0.0018	0.0018	0.0021	A
0.0032	0.9592	0.0026	0.0054	B
0.0019	0.0008	0.8974	0.0015	C
0.0016	0.0061	0.0040	0.8377	D
A	B	C	D	

(c) Staged Baseline

0.9605	0.0008	0.0016	0.0023	A
0.0014	0.9592	0.0000	0.0080	B
0.0030	0.0000	0.8974	0.0000	C
0.0027	0.0075	0.0000	0.8377	D
A	B	C	D	

(d) Staged Distance Penalty

Figure 5: Fitted productivity estimates for the distance-based simulation under three penalty regimes (i.e. joint baseline, staged baseline, staged penalty). True parameter values are included for comparison.

Application to COVID-19 - Local Parameter Recovery

Parameter	LA	PHX	DAL	MIA
μ	49.06 (2.856) [43.47, 54.66]	1.98 (0.576) [0.85, 3.11]	8.09 (1.042) [6.05, 10.14]	20.57 (1.874) [16.90, 24.25]
K	1.08 (0.009) [1.07, 1.10]	1.19 (0.010) [1.17, 1.21]	1.01 (0.010) [0.99, 1.03]	0.96 (0.009) [0.94, 0.98]
β	0.61 (0.019) [0.57, 0.65]	1.18 (0.042) [1.10, 1.26]	1.30 (0.096) [1.11, 1.49]	1.63 (0.074) [1.48, 1.77]
p	0.33 (0.009) [0.31, 0.34]	0.27 (0.013) [0.25, 0.30]	0.30 (0.030) [0.24, 0.36]	0.22 (0.017) [0.19, 0.25]

Table 4: Fitted Stage 1 local parameters with (standard errors) and [95% confidence intervals] for COVID-19 data trained on 104 days from March 12, 2020 to June 24, 2020.

Application to COVID-19 - Productivity Recovery

0.6571	0.0702	0.7581	0.3617	LA
0.0097	1.1489	0.0000	0.0000	PHX
0.0633	0.1184	0.4377	0.0000	DAL
0.0044	0.0608	0.1380	0.7950	MIA
LA	PHX	DAL	MIA	

(a) Joint Baseline

1.0837	0.0308	0.0000	0.0752	LA
0.0000	1.1920	0.0000	0.0000	PHX
0.0000	0.0138	1.0097	0.0000	DAL
0.0000	0.0416	0.0000	0.9599	MIA
LA	PHX	DAL	MIA	

(b) Staged Baseline

1.0837	0.0325	0.0000	0.0395	LA
0.0000	1.1920	0.0000	0.0000	PHX
0.0000	0.0114	1.0097	0.0000	DAL
0.0000	0.0267	0.0000	0.9599	MIA
LA	PHX	DAL	MIA	

(c) Staged Distance Penalty

1.0837	0.0315	0.0000	0.0420	LA
0.0000	1.1920	0.0000	0.0000	PHX
0.0000	0.0097	1.0097	0.0000	DAL
0.0000	0.0276	0.0000	0.9599	MIA
LA	PHX	DAL	MIA	

(d) Staged Mobility Penalty

Figure 6: Fitted productivity estimates under different penalty regimes for observed COVID-19 data. Columns indicate origin while rows indicate destination.

Application to COVID-19 - Productivity Recovery

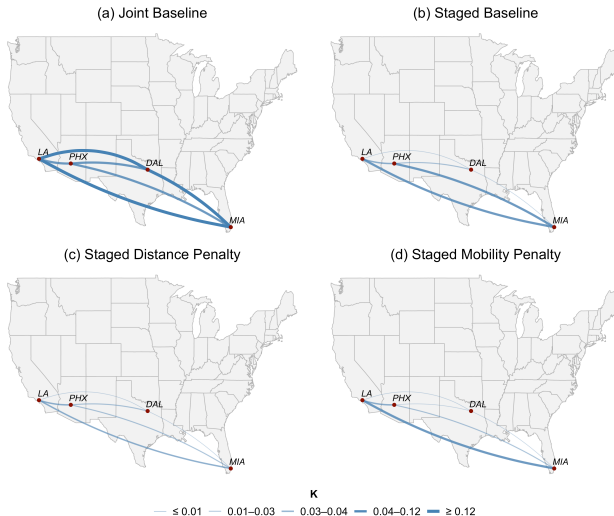


Figure 7: Fitted inter-county productivity rates under four different estimation regimes.

Application to COVID-19 - Predictive Performance

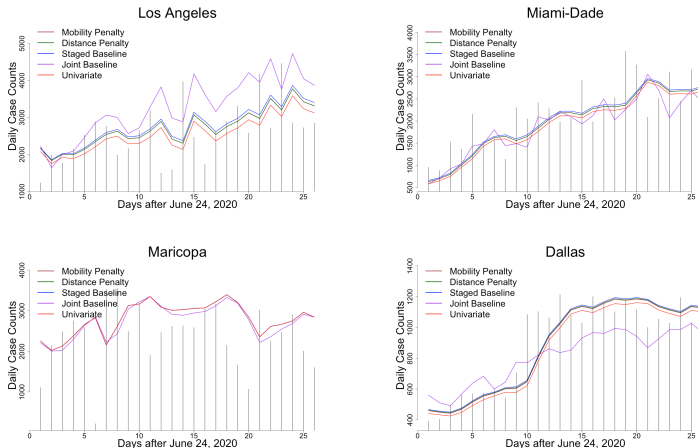


Figure 8: Daily recorded COVID-19 case counts (bars) with five estimation method predictions (curves) overlaid for each location from June 25, 2020 to July 20, 2020. All plots are fitted to observed COVID-19 data [12].

Estimate	NLL	RMSE	$\hat{K}_{i=j}$	$\hat{K}_{i \neq j}$
Joint Baseline	13642	795	0.76	0.132
Univariate	11458	682	1.06	0
Staged Baseline	10961	676	1.06	0.013
Staged Distance Penalty	11060	676	1.06	0.009
Staged Mobility Penalty	11057	676	1.06	0.009

Table 5: Pooled negative log-likelihood (NLL), pooled Root Mean Squared Error (RMSE), mean diagonal (local) productivity estimates ($\hat{K}_{i=j}$), and mean off-diagonal (cross) productivity estimates ($\hat{K}_{i \neq j}$) under five estimation frameworks for observed COVID-19 data.

Future Research Plan

Current Limitation: Currently, parameters are time-invariant, statically structured to explain transmission over the course of a dynamic pandemic.

Proposed Enhancement: Allow parameters to vary piecewise by statistically identifying significant change-points and partitioning the time series accordingly.

- Scale to the entire course of a pandemic, not merely 130 days.
- Determine change-points by detecting trend changes:
 - Smooth case counts (7-day)
 - Estimate change-points m
 - Estimate $\mu_i^{(m)}, K_{ij}^m$ for all i, j, m

Scaling in Time Cont.

Change-points are likely to exist as a consequence of:

- Policy changes (e.g., quarantines, mandatory mask mandates)
- Emergence of variants (e.g., Omicron)
- Seasonality (e.g., winter vs. summer trends)
- Mobility shifts (e.g., virtual work adoption, airport travel patterns)

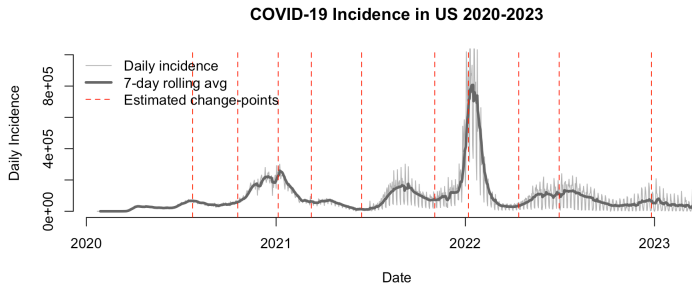


Figure 9: COVID-19 data of total daily incidence in the USA were obtained from the NY Times COVID-19 GitHub repository [12].

Scaling in Time Cont.

Breakpoints are estimated by fitting a piecewise-linear regression model to 7-day smoothed incidence.

$$\lambda_i(t|\mathcal{H}_{t-}) = \mu_i^{(m)} + K_{ij}^{(m)} \sum_{s < t} \phi_{\text{local}}(t, s; \beta_i, p_i) N_i(s) + \sum_{j \neq i} K_{ij}^{(m)} \sum_{s < t} \phi_{\text{cross}}(t, s; \bar{\beta}_i, \bar{p}_i) N_j(s) \quad (9)$$

where $m = 1, \dots, M$ denotes disjoint time segments and $m - 1$ is used as **priors** to initialize segment m . Change-points are estimated globally and shared across locations rather than locally for the purposes of scalability, though local segmentation would be a natural extension. Event history persists across segments via triggering kernels, in alignment with infectious disease dynamics.

Current Limitation: A mere four-node network has been studied up to this point, neglecting many locations in order to mitigate computational expense.

Proposed Enhancement: Scale the model to efficiently handle many nodes, either state- or country-wide.

- CA has 58 counties.
- USA has approximately 3,200 counties.

To reduce computational load, the following methods are proposed:

- Directional covariate gates.
- Parallelization across locations.
- Modulating μ , K by a population density scaling factor.
- Residual-based gating.

Population Density

Total cases per person

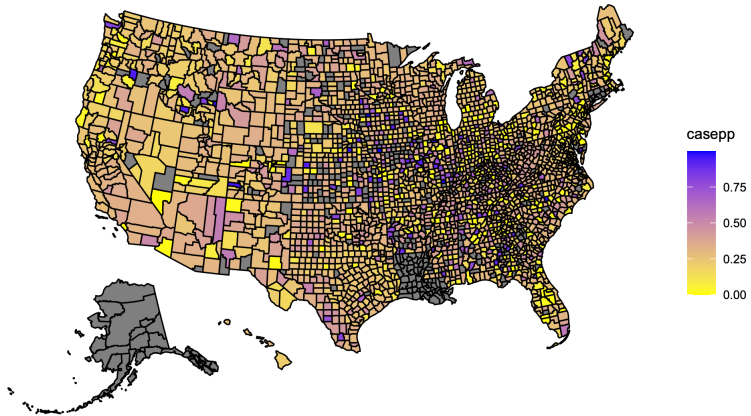


Figure 10: US map of COVID-19 cases standardized by county population. COVID-19 cases are cumulated from 2020-2023, while county population is set to 2021 rates.

Proposition 1 (Stability): The multivariate Hawkes process is stable.

Proposition 2 (Consistency): Assuming stability and Stage 1 estimators are consistent, Stage 2 estimators are consistent up to regularization bias.

Proposition 3 (Error): The estimation error of the cross-excitation parameter K_{ij} decomposes into

$$\hat{K}_{ij} - K_{ij} = \underbrace{(K_{ij}^* - K_{ij})}_{\text{Stage 1 error}} + \underbrace{\mathbb{E}[\hat{K}_{ij} \mid \text{Stage 1}] - K_{ij}^*}_{\text{regularization bias}} + \underbrace{\hat{K}_{ij} - \mathbb{E}[\hat{K}_{ij} \mid \text{Stage 1}]}_{\text{sampling noise}} \quad (10)$$

where K_{ij}^* is the oracle estimator

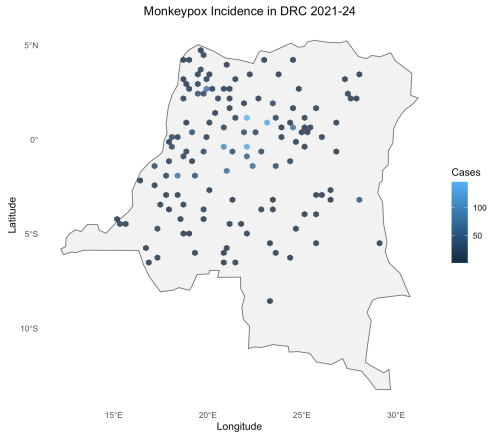


Figure 11: Monkeypox data in the Democratic Republic of the Congo 2022-2024.

Conclusion

Conclusion

Current problem:

- Overly zealous and biased cross-productivities as a result of naturally similar temporal patterns.

Proposed solution:

- Staged estimation
- Covariate-informed penalties
- Time-varying parameters
- Modulate with population density
- Smart spatial scaling

Anticipated result:

- Improved parameter recovery and predictive performance.
- Extend conventional MHPs to be covariate-informed & scalable to large networks.

Milestones:

1. Scale in time

- Statistically identify notable change points over the course of the COVID-19 pandemic (March 2020 - May 2023)
- Estimate parameters for each disjoint time segment m

2. Scale in space

- Directional covariate gates
- Parallelization
- Modulate μ, K by population density
- Residual-based gating

3. Staged estimator

- Stability
- Consistency
- Error decomposition

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